






# Siemens PAVE360

Automotive system development using accelerated pre-silicon simulation environment

# Decisions made today have very long-term consequences, the SDV needs a new development methodology

## Traditional vehicle challenges

-  **Longevity**  
HW lifetime >15 years
-  **Field updates**  
SW updates & feature upgrades for >7 years
-  **Long development cycle**  
HW specification ready  
~3 years before production

...will only get worse thanks to...



**Complexity of SDV**  
Hyper competitive  
Shorter design cycles

...meaning..



It **takes years** for new physical hardware  
  
....too late for SW development

# Regardless of whether they are developing a semiconductor, ECU or even full vehicle architectures, automotive players face the same challenges



## Automotive Challenge

**Long, expensive development cycle**



Conflicts with speed of innovation, increasing vehicle complexity

**Integration storm**



Closed solutions from multiple vendors increases integration effort

**Lack of “full system view”**

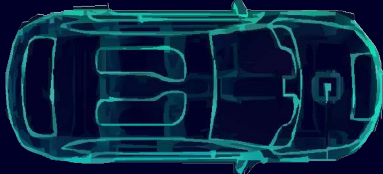


How can performance of entire system be measured, across multiple teams?

**Continuous updates & integration**



Integration only starts on system completion, updates are costly



## PAVE360 digital twin delivers

**Shift left! Develop SW pre HW**



Digital twin enable parallel HW and SW development

**Easy system configuration**



Integrate digital twin, HW and tools from multiple vendors

**Metrics to drive decision making**



Generate a unique set of metrics, for mixed domains

**Early start for system integration**



Integrates elements at every stage of development

# That's why Siemens, Arm and ecosystems partners are working together To "shift-left" the SDV

**SIEMENS**

Shift the SDV left with **PAVE360** accelerated pre-silicon development environment

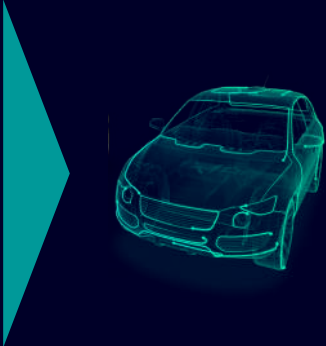
**arm**

Uses PAVE360 to enable developers to access the new **Arm Cortex-A720AE** pre-hardware

**aws**

Hosts PAVE360 to provide **unprecedented simulation speeds** on the cloud for the Cortex-A720AE

First partners are developing software for the SDV and the Arm Cortex-A720AE today, with PAVE360



BlackBerry QNX, Elektrobit, sensory, TATA TECHNOLOGIES, TIER IV

## Arm's ecosystem support for virtual prototyping Siemens provide first Arm A720 AE CPU support

arm

“ Today, in a series of industry firsts, Arm and our ecosystem are unveiling the latest Arm Automotive Enhanced (AE) processors alongside new virtual platforms, all made available to the industry from day one to accelerate automotive development cycles by up to two years.”

SIEMENS

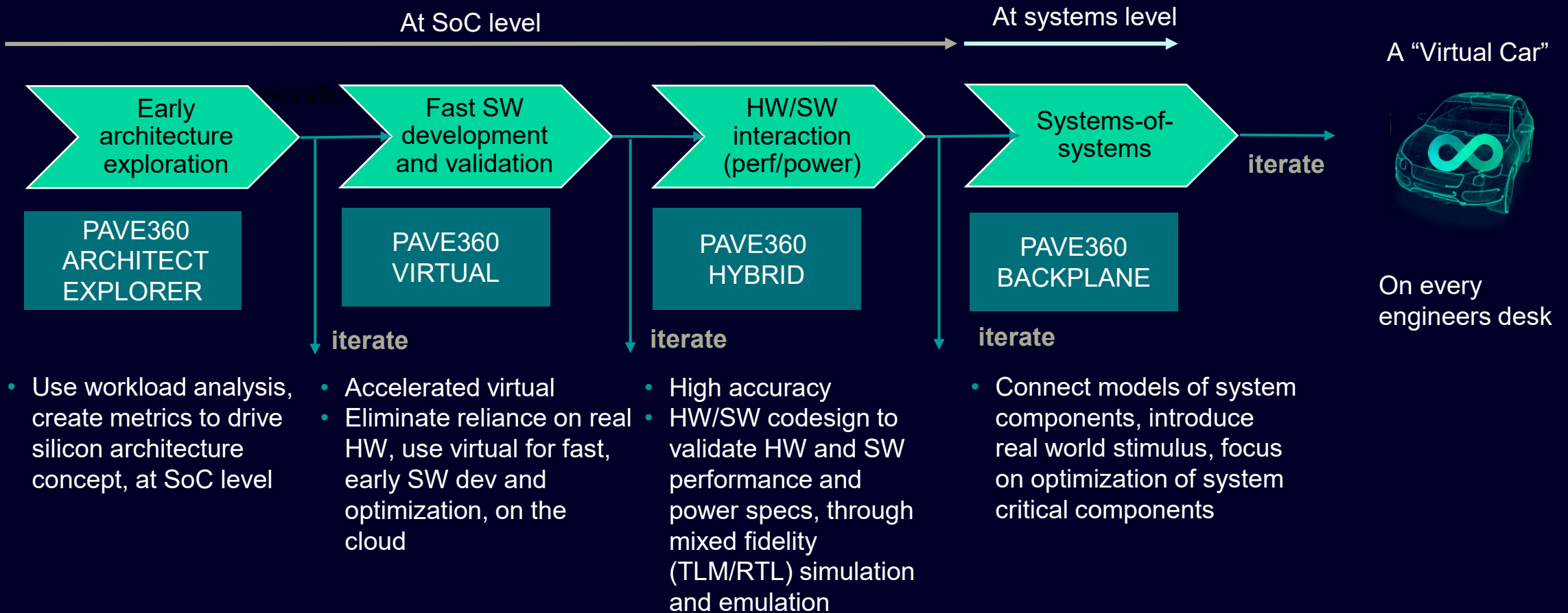
“Our partnership with Arm, supporting an accelerated simulation environment with Cortex-A720 AE CPU, is helping to address automotive industry challenges by reducing time-to-market for SDV software through the availability of accelerated automotive platforms well ahead of silicon.”



Source: <https://www.arm.com/markets/automotive>

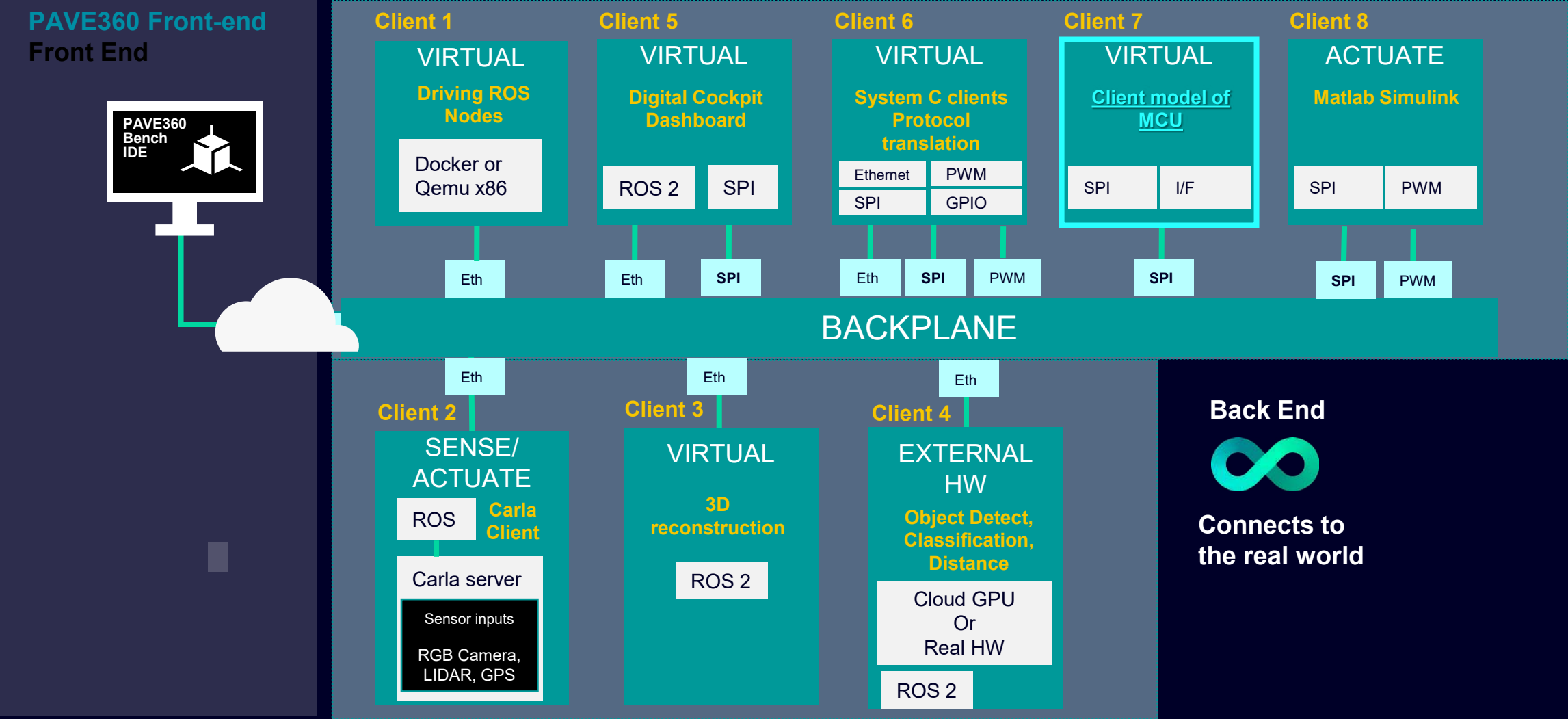
# Shift Left methodology, a digital twin that grows with your design

Pre-silicon digital twin 

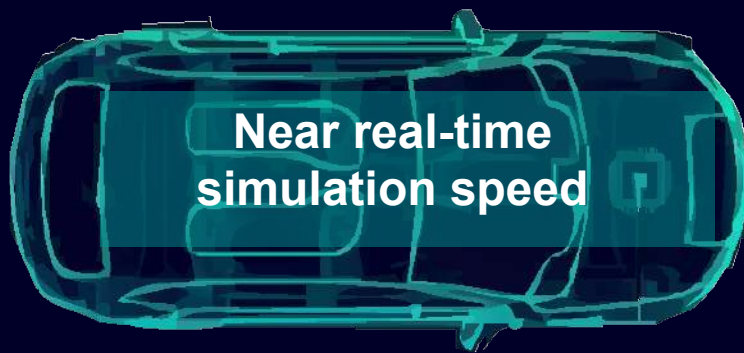
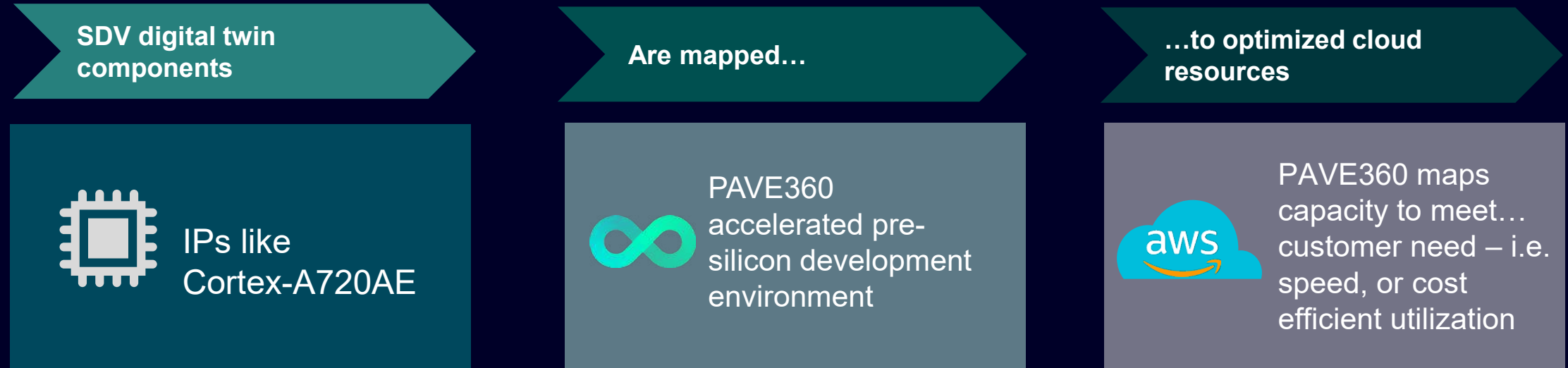


# Customer Success Story: Major APAC Tier 2 Silicon Vendor

## Validate new concepts for next gen MCUs in real world context



# Accelerated pre-silicon SW simulation development environment



## What does this mean for software application developers?

- Embedded environment as close to the target SoC as you'll get
- Native cloud development of complex vehicle software
- In familiar IDE based environment
- Near real-time simulation speed, much faster than traditional methods



# Accelerated pre-silicon development environment Early Access Release

## Arm Cortex-A720 AE Virtual SoC model

- HW:**
- Arm Cortex A720 AE x14
  - GIC V3
  - Memory
  - Virtual Storage
  - Virtual Networking
  - PI011 UART
- SW:**
- SOAFEE EWAOL Linux
  - TFLite + Benchmarks
- Tools:**
- PAVE360 Bench IDE for Metrics & Analysis

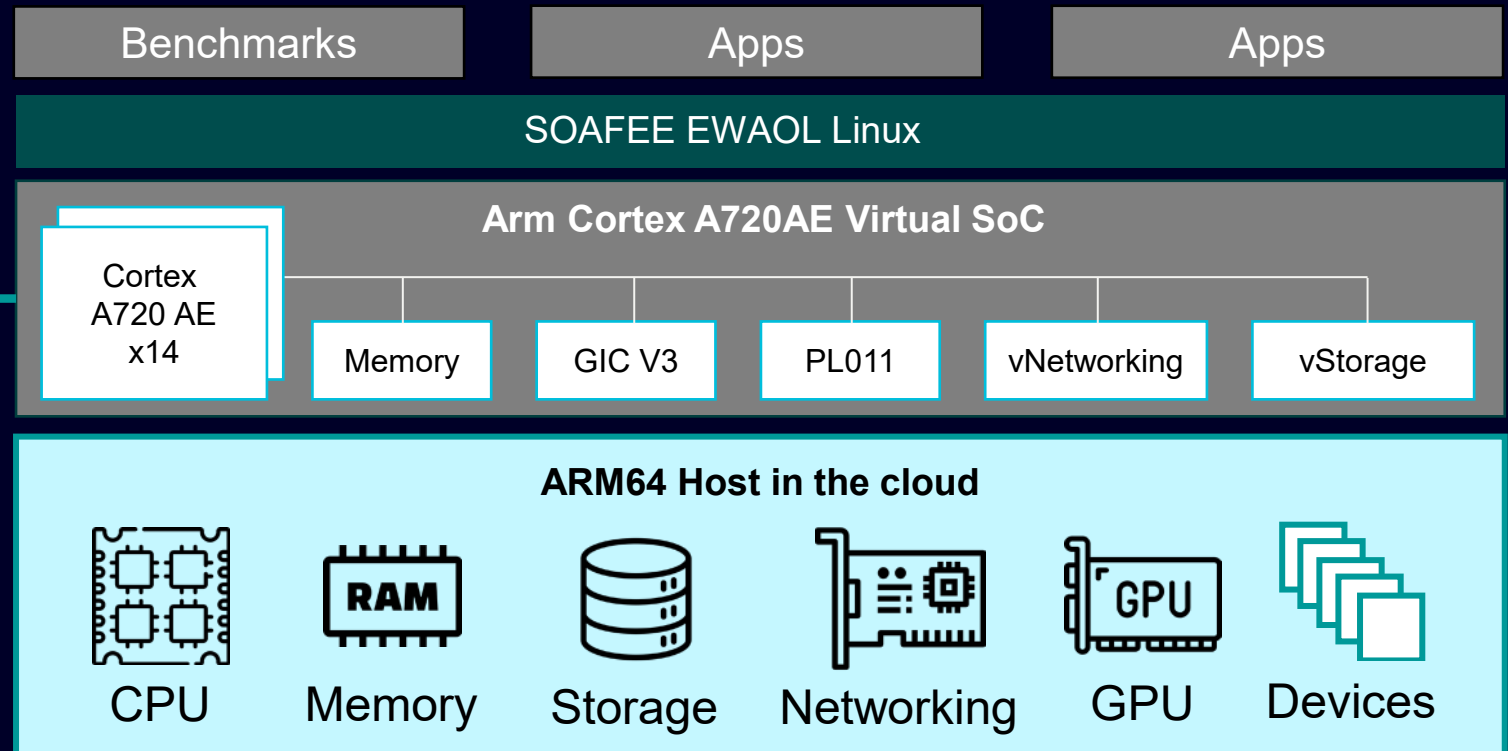


**Web Console / REST API**

System Configuration Console, ... access

**PAVE360 Bench IDE**

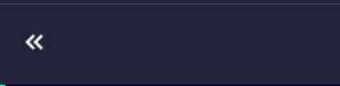
Trace Configuration Metrics Visualization





## **PAVE360**

Accelerated pre-silicon  
development  
environment demo



Home

Platform

Firmware

Serial Console

Help

Contact Us

Toggle Theme

About & legal information

## Welcome to Arm® Cortex-A720AE Virtual SoC Reference Platform

A web interface to bring up supported reference software environments for the Arm Cortex-A720AE Virtual SoC model.

> [Get Platform Details](#)

> [Upload Firmware Images](#)

> [Connect to Serial Console](#)

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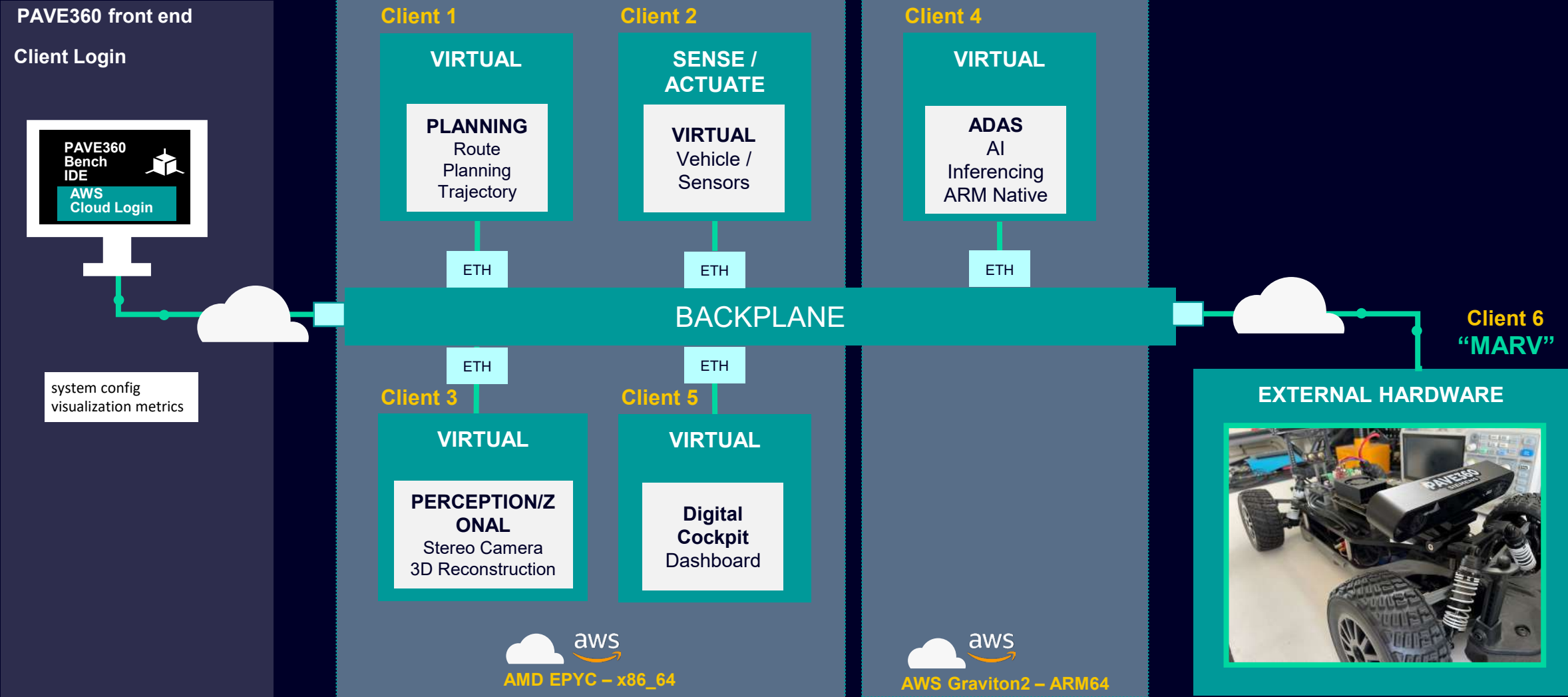


**PAVE360**

External hardware  
demo

# PAVE360 Multi Client Cloud Autonomous ADAS Reference Design

## System-of-systems with real world stimulus optimized using cloud resources



# PAVE360 system-of-system clients in more depth



Explore vision-based 3D detection algorithm for production

## Client 1

### PLANNING

Route  
Planning  
Trajectory

Destination route planner and provides steering, acceleration and braking

## Client 2

### SENSORS / ACTUATORS

CARLA  
Simulator  
Vehicle /  
Sensors

CARLA driving simulator with environment and vehicle with sensors

## Client 3

### PERCEPTION ZONAL

Stereo Camera  
3D Reconstruction

3D detection running in real-time on zonal controller. Without GPU or accelerators.

## Client 5

### VISUAL

Digital Cockpit  
Dashboard

Digital cluster displaying ADAS and vehicle information



AMD EPYC – x86\_64

## Client 4

### PERCEPTION CENTRAL

ADAS  
AI Inferencing  
Accelerated

3D detection DL model on central ADAS controller.

Deployable to accelerators: NPUs, GPU or CPU. Runs natively on Arm Graviton2.



AWS Graviton2 – ARM64

## Client 6

### EXTERNAL HARDWARE

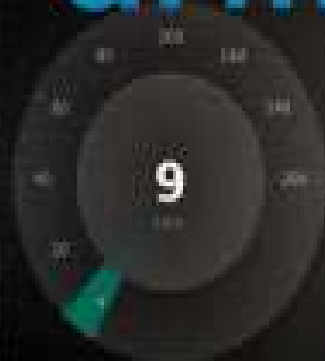


### MARV



Validate steering, acceleration and braking actuators

arm



SIEMENS



aws

Distance (m)  
Type

```

[INFO] [17.01.2022 10:00:00.000] [rosCpuUsageInterface]: all nodes
received status from gear-1: [roscpp-2.0.0] status: 0.00
[INFO] [17.01.2022 10:00:00.000] [rosCpuUsageInterface]: all nodes
received status from 'left': [roscpp-2.0.0] status: 0.00
[INFO] [17.01.2022 10:00:00.000] [rosCpuUsageInterface]: all nodes
received status from 'right': [roscpp-2.0.0] status: 0.00
[INFO] [17.01.2022 10:00:00.000] [rosCpuUsageInterface]: all nodes
received status from gear: [roscpp-2.0.0] status: 0.00

```

Distance (m)  
Type





# PAVE360

## SDV success story





Develop

Serial Console

```

root@sws11:~/svind/armml # ./runref.sh
Keyboard device not found
mml file set to: data/node1.tflite
Inference will execute 1 inference(s)
Can't load libOpenCL.so: libOpenCL.so cannot open shared object file: No such file or directory
Can't load libGLES_mali.so: libGLES_mali.so cannot open shared object file: No such file or directory
Can't load libmali.so: libmali.so cannot open shared object file: No such file or directory
Couldn't find any OpenCL library.
/home/sws11/ai-apps/annotate/streamline/annotate.c/gator_funcr540: warning: Not connected to gator, the applica
tion will run normally but Streamline will not collect annotations. To collect annotations, please verify you are running gator 5
.18 or later and that Streamline is disabled.

Mali information:
inputTensorName[0] = input
outputTensorName[0] = MobileNetV2/Predictions/Softmax

Inference are running: 1

Inference time: min=99871us max=99871us avg=99871us
Inference time: 1 (1712736642 - 1712736641) seconds
root@sws11:~/svind/armml #

```

VOICES on arm

# Thanks!

Want to find more about  
**PAVE360?**



## Disclaimer

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